Reversible work transition state theory: application to dissociative adsorption of hydrogen

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Received 5 August 1994; accepted for publication 25 October 1994

Abstract

A practical method for finding free energy barriers for transitions in high-dimensional classical and quantum systems is presented and used to calculate the dissociative sticking probability of H₂ on a metal surface within the transition state theory. The reversible work involved in shifting the system confined to a hyperplane from the reactant region towards products is evaluated directly. Quantum mechanical degrees of freedom are included by using Feynman path integrals with the hyperplane constraint applied to the centroid of the cyclic paths. An optimal dividing surface for the rate estimated by the transition state theory is identified naturally in the course of the reversible work evaluation. The free energy barrier is determined relative to the reactant state directly so that an estimate of the transition rate can be obtained without requiring a solvable reference model for the transition state. The method has been applied to calculations of the sticking probability of a thermalized hydrogen gas on a Cu(110) surface. The two hydrogen atoms and eight surface Cu atoms were included quantum mechanically and over two hundred atoms in the Cu crystal where included classically. The activation energy for adsorption and desorption was determined and found to be significantly lowered by tunneling at low temperature. The calculated values agree quite well with experimental estimates for adsorption and desorption. Dynamical corrections to the classical transition state theory rate estimate were evaluated and found to be small.

Keywords: Adsorption kinetics; Chemisorption; Computer simulations; Equilibrium thermodynamics and statistical mechanics; Models of surface chemical reactions

1. Introduction

The dissociative adsorption of molecules on surfaces of solids is of central importance in surface catalysis and has been extensively studied both experimentally and theoretically. Hydrogen adsorption on copper surfaces has become “the classic example of activated dissociative adsorption of a molecule at a surface” [1]. Many experimental studies have made use of molecular beams with molecules in a selected initial state impinging on the surface. Theoretical studies have focused on classical trajectory calculations and quantum wavepacket
propagation to explore the dissociative sticking dynamics given a well defined initial state of the molecule [1]. A great deal of qualitative insight has been gained, but many questions remain open. On the theoretical side, the problem is that full quantum mechanical treatment of all six hydrogen degrees of freedom is impractical with present computers and currently available techniques for quantum wavepacket propagation. The theoretical work has therefore largely been confined to quantum calculations on lower-dimensional model systems [2–4] or mixed quantum and classical treatment [5]. Not only is a six-dimensional wavepacket propagation a big order, but such a calculation would need to be repeated many times to average over the surface vibrational degrees of freedom to get a single value of the sticking probability. Low-dimensional simulations have demonstrated clear quantum effects [1,2], and calculations in higher dimensions have indicated that dimensional effects might be equally important [3,4].

We report here on a fully quantum and thermally averaged simulation of the dissociative sticking of H₂ on Cu(110). The large number of degrees of freedom can be included at the expense of the amount of information obtained about the dynamics. We apply the transition state theory, a statistical theory of rates, to this problem and study entropic and quantum effects on the sticking probability. Quantum effects are included by Feynman path integrals (FPIs) which implicitly include thermal averaging over quantum states [6]. The simulation mimics a thermodynamic experiment, where the impinging molecules have a thermal energy distribution at the temperature of the substrate. This experiment has been carried out in the laboratory of Campbell and coworkers [7] who obtained the thermodynamic activation barrier for dissociative adsorption from the temperature dependence of the sticking probability. Our simulations using a rather simple model potential surface show a clear onset of a quantum mechanical regime as the activation energy drops at a temperature around 400 K. The experimental measurements of the sticking coefficient were taken slightly above this transition temperature.

The method we present here involves evaluation of reversible work to determine the free energy of the system along the reaction coordinate and, in particular, the free energy barrier for the transition. Traditional methods for evaluating free energy differences between two states, in particular a transition state and a reactant state, involve integration (using Monte Carlo sampling) over a parameter λ which smoothly converts the potential from one state to another [8]. The advantage of the present technique is that the transition state need not be known beforehand, and since the integration is over the reaction coordinate the intermediate states in the calculation have some physical significance. Voter [9] has presented a technique for direct Monte Carlo calculation of free energy differences between separated, localized states by translating one to overlap the other. This method eliminates the need for sampling intermediate states but again requires a priori knowledge of the transition state, and can have sampling problems if the transition state potential is shaped much differently than a slice of the reactant state potential.

The method described here has previously been applied to calculate transition rates in a model system consisting of an Eckart barrier coupled to a harmonic oscillator [10]. Even in such a small system, the reversible work evaluation was more efficient than calculation of the partition function with a harmonic reference. Here we give expressions directly applicable to large systems and apply the method to hydrogen dissociative adsorption. Preliminary results of these calculations have been presented elsewhere [11].

The organization of this paper is as follows. We first discuss classical transition state theory (TST) in Section 2. Then quantum TST is discussed in Section 3. In Section 4 we present a derivation of the equations required for calculating free energy barriers in classical systems by evaluation of reversible work. The application of these equations involves statistical sampling of forces acting on the system while constraints are applied. Following Gillan [12], we then generalize these expressions to quantum systems in Section 5 by representing quantum particles by Feynman path integrals and applying the constraints to the path integral centroids. In Section 6 we discuss the hydrogen dissociative sticking problem and present our results on the H₂–Cu(110). A summary is presented in Section 7.
2. Classical transition state theory

Transition state theory is a method for estimating rate constants of transitions, for example, chemical reactions and diffusion events [13–15]. It is applicable to slow transitions or rare events. It is a statistical theory, but is based on dynamics. The underlying idea is that the equilibrium density at the reaction’s transition state – a statistical quantity – is proportional to the reaction rate – a dynamical quantity. A central aspect of transition state theory is the identification of a dividing surface separating the initial state (the reactants) and the final state (the products). Such a dividing surface is frequently referred to as the “transition state”. All possible transitions from the initial state to the final state take the system through the dividing surface.

A well-chosen dividing surface also separates the initial and final states in terms of dynamics. A system at such a transition state may become either reactants or products, and once it becomes one or the other, it is likely to remain so for a much longer time than it spent near the transition state. Thus, the system’s character in the future is strongly dependent on what it does during its brief visit to the transition state. This makes the transition state and what happens there of central importance.

The system consists of the degrees of freedom of primary interest and all degrees of freedom to which they are coupled. For instance, in the H₂ dissociation on Cu, the system consists of both the dimer and the Cu lattice. The hydrogens move furthest and are the primary degrees of freedom, and the reaction’s progress – the reaction coordinate – is determined by the hydrogens’ positions. The surface degrees of freedom are also specifically included but do not enter the reaction coordinate or the definition of the transition state; they are effectively a bath.

2.1. The central assumptions of TST

The first central assumption of transition state theory is that the reactants have a Boltzmann distribution of energy in every degree of freedom and that the rate of transition is low enough that this distribution is maintained.

As a consequence, the system will have a Boltzmann distribution of energy at the dividing surface, even if the system does not exchange energy with a bath during its climb up the barrier. The density at the barrier is low because the barrier turns most trajectories around. Those trajectories which do make it to the dividing surface, however, have a momentum and spatial distribution at the barrier which is Boltzmann at the reactant temperature except that states originating from products are missing [14,16]. It is important to realize that TST does not need to make any assumptions about the ability of the system to achieve an equilibrium distribution at the dividing surface.

If the reactants are specifically prepared in a non-Boltzmann distribution, for example, in a molecular-beam experiment where different reactant modes may be at different temperature, or if the surface and adsorbate temperatures are different, then the system – consisting of both the incident molecule and the surface – is not at thermal equilibrium, and TST does not apply. We calculate here the sticking probability of a thermalized gas, where the gas and surface temperature are the same.

The second central assumption of transition state theory is that the system crosses the dividing surface only once in going between the reactant and product states. A reactive trajectory is one which takes the system from steady-state reactants to steady-state products. The actual reaction rate depends on the density of reactive trajectories at the dividing surface. Transition state theory assumes that any crossing of the dividing surface in the direction from reactants to products is a reactive trajectory. In reality, trajectories can cross the dividing surface many times. Any trajectory that crosses the dividing surface an even number of times, starting from either side, is not reactive, but is counted in TST. Further, a trajectory which crosses several times before ultimately reacting is reactive, but is counted several times in TST while only forming one product. As a result, the TST estimate of the rate is always an overestimate, but in favorable cases and for a good choice of the dividing surface TST can give an estimate that is nearly exact.
The fraction of trajectories that have been overcounted in the TST estimate can be found only by studying the dynamics of the system. Transition state theory assumes that the probability, $\kappa$, of continuing to products, once the dividing surface is reached with a momentum directed towards products, is unity. If the system sometimes recrosses the dividing surface, $\kappa < 1$. For a given choice of the dividing surface a transmission coefficient, $\kappa$, can be found such that the exact rate constant is $k_{\text{exact}} = \kappa k_{\text{TST}}$.

For a good choice of the dividing surface, $\kappa$ is as large as possible, and $k_{\text{TST}}$ is as close as possible to the actual rate constant. A dividing surface far into the reactant state would result in many crossings, most of which would lack enough energy to cross the barrier and would soon recross it. For this dividing surface, $\kappa \ll 1$, and $k_{\text{TST}}$ is a poor estimate of the rate. Similarly, a dividing surface far into the product state would be a poor choice, because most of the density there comes not from paths that have recently reacted, but from products that have recently tried and failed to back-react.

While TST predicts that the sticking coefficient depends only on interatomic forces and not on atomic masses, the recrossings can be mass dependent, for example, if the products re-desorb because energy is not redistributed between different modes on the time-scale of the reaction. This phonon coupling is mass-dependent, and hence can lead to kinetic isotope effects that are not predicted by TST.

Below, we describe studies we have carried out of dynamical trajectories for H$_2$ dissociative sticking on Cu(110). We found that dynamical corrections play a minor role in this system. TST can therefore be expected to give reliable estimates of the sticking coefficient.

2.2. Variational transition state theory

Since classical TST gives an upper bound to the rate, and can be applied to any dividing surface between reactants and products, it is possible to search for the dividing surface for which the estimated rate becomes a minimum; this estimate is closest to the true rate. This dividing surface will have the fewest recrossings.

This optimization of the TST estimate is called variational transition state theory (VTST) [17]. The variation of the plane can be done separately at different temperatures, or at different initial reactant momenta, or by making the dividing surface non-planar, any added flexibility giving an improved rate estimate. There exist hypersurfaces that separate the dynamics completely; in general, these are curved, and different for each reactant energy [13,18]. If such a hypersurface could be found, the rate associated with it would be the exact reaction rate: there would be no recrossings. However, for high-dimensional systems, finding an optimal surface, even within a restricted set (such as hyperplanar surfaces), is a non-trivial problem.

2.3. The transition state partition function

Fig. 1 shows a reaction path, $\Gamma(s)$, between reactants and products, parameterized with reaction coordinate $s$. If $N_p$ is the number of atoms of primary interest; that is, those that undergo a significant displacement during the transition, then $\Gamma(s)$ is a $3N_p$-dimensional vector pointing at position $s$ on the path. The reaction path is defined in terms of these coordinates and is independent of all others. The dividing surface, $Z$, is a ($3N_p - 1$)-dimensional cut through the $3N_p$-dimensional system. In the case of the H$_2$/Cu system, only the hydrogens change position significantly during the reaction, so the dividing surface is a five-dimensional cut through the six-dimensional H$_2$ system. All degrees of freedom independent of $\Gamma$ comprise the bath. In the H$_2$/Cu system, the bath consists of all the Cu atoms. If, for instance, two of the Cu atoms moved significantly to enable the dissociation to happen, the reaction path would include those Cu atoms, and all other Cu atoms would be the bath.

The dividing surface has one dimension fewer than does the reactant state. A transition state with the same dimensionality as the reactant can be defined by arbitrarily introducing a small width $\delta$ to the dividing surface. Eventually this width is cancelled out and does not enter the final expressions. The probability of finding the system at the transition state is $Q^*/Q^R$. The transition state partition function can be written as $Q^* = Q^\dagger\delta$, 


\[ \bar{x}_0 = \frac{1}{P} \sum_{i}^P x_i \]  

(7)

at a given point, and taking the average over the remaining quantum degrees of freedom and classical bath degrees of freedom. In particular, he evaluated the probability of finding the centroid at the saddle point of the potential surface between reactants and products, relative to the probability of finding the centroid in the reactant region. By gradually shifting the centroid constraint from the reactant region up to the saddle point and monitoring the reversible work, he obtained a free energy difference. A rate estimate was obtained by assuming the rate is proportional to the relative density of the centroid at the saddle point.

In one-dimensional systems the classical limit of this estimate agrees with classical TST. However, in higher dimensions it does not. The centroid in Gillan’s formulation is confined to a point rather than to a dividing surface; the transition rate is related to the centroid density at two specified points [10,12]. This estimate includes bath degrees of freedom, and various FPI chain configurations of the quantum particle (thus it picks up some tunneling and zero-point energy effects), but it does not include averaging over centroid degrees of freedom perpendicular to the reaction path. Thus, it does not fully include effects due to varying width of the reaction channel.

Following Gillan’s idea, Voth, Chandler, and Miller (VCM) [22] provided a quantum generalization of traditional TST by replacing the classical coordinate in Eq. (1) by the centroid coordinate of the quantum particle. Again, a constrained FPI formalism was used, but with the centroid restricted to a multidimensional dividing surface rather than to a point. The calculations were done by explicit evaluation of the partition function, using an analytically solvable reference problem. This method was applied to calculations on a restricted geometry of the reaction \( \text{H} + \text{H}_2 \rightarrow \text{H}_2 + \text{H} \) and found to give results in good agreement with more accurate calculations.

Messina, Schenter, and Garrett (MSG) [24,25] generalized the VCM expression and allowed for variational optimization of non-planar and momentum-dependent dividing surfaces. The dividing surface was chosen to minimize the calculated rate obtained by direct evaluation of the dividing surface partition function. MSG is a quantum analogue of classical VTST. In these calculations a Monte Carlo sampling procedure is used to find the partition functions explicitly.

These centroid density methods have been applied to various test problems and have been shown to give good rate estimates. Transitions in three-dimensional systems involving one quantum particle have also been studied using these techniques. Gillan studied the diffusion of a hydrogen atom in bulk metals [12]. Mattsson, Engberg, and Wahlström [29] and Sun and Voth [30] studied the diffusion of a hydrogen atom on Ni(100) and Cu(100) surfaces, respectively.

We describe below a different computational method, reversible work based TST, for carrying out classical and quantum TST calculations. For classical systems the results are equivalent to VTST. For quantum systems, the results are equivalent to MSG. The advantage of the reversible work formulation is that the method can more easily be applied to high-dimensional systems. After describing the method and its foundation, first as it applies to classical systems (Section 4) and then as it applies to quantum systems (Section 5), we then describe an application to \( \text{H}_2 \) dissociative adsorption, a reaction path involving two quantum particles (the H atoms) and a bath involving eight quantum particles (surface Cu atoms) and a couple of hundred classical particles (Section 6). This is by far the largest application of QTST we are aware of. Our conclusions are given in Section 7.

4. Reversible work formulation of classical TST

\( k^{\text{TST}} \) is written in terms of a partition function ratio, or a free energy difference. The free energy can be calculated by the method of reversible work rather than by calculating the partition functions explicitly. The
rate constant, Eq. (4), can also be written
\[ k^{\text{TST}} = \frac{k_B T}{\sqrt{2\pi \mu k_B T}} \frac{Q^R}{Q^\ddagger} \frac{Q^\ddagger}{Q^R}, \]
where we have introduced \( Q^Z^R \) a partition function for the system confined to a reference hyperplane \( Z^R \) in the reactant region. \( Q^Z^R / Q^R \) has units of inverse length. \( Q^\ddagger / Q^Z^R \) is unitless and, if there are no recrossings of the transition state, is the reaction probability: (number of reactions)/(number of attempts).

The rate is \((\text{average positive velocity}) \times (\text{average reciprocal length}) \times (\text{reaction probability})\). For surface adsorption, \( Q^\ddagger / Q^Z^R \) is the sticking coefficient.

4.1. Relative probability and free energy

The reaction probability can also be written in terms of the free energy, \( A \), of the transition and reference planes:
\[ \frac{Q^\ddagger}{Q^Z^R} = e^{-\beta(A^\ddagger - A^Z^R)} \],
\[ \Delta A \equiv A^\ddagger - A^Z^R. \]
In the reversible work evaluation the hyperplane is moved stepwise from \( Z^R \) to \( Z^\ddagger \), as indicated in Fig. 1b, and the free energy difference, \( \Delta A \), is accumulated at each step.

Fig. 1b shows a progression of hyperplanes \( Z_s \) defined along the entire reaction path \( \Gamma_s \) between reactants and products. Given a path, the sequence of hyperplanes can be constructed by choosing the tangent vector of the path \( \frac{d}{ds}\Gamma_s \), at various points along the path as the normal to a hyperplane associated with that reaction coordinate
\[ n_s \equiv \frac{d}{ds}\Gamma_s / \left| \frac{d}{ds}\Gamma_s \right|. \]
The progression of the hyperplane has to be gradual enough that a first order evaluation of the free energy difference will be accurate. As the reaction coordinate is incremented by \( ds \), where
\[ ds = \| \Gamma_{s+ds} - \Gamma_s \|, \]
the hyperplane intersection with the path moves from \( \Gamma_s \) to \( \Gamma_{s+ds} \) and the normal vector changes from \( n_s \) to \( n_{s+ds} \).

It is convenient to introduce a coordinate system aligned with the hyperplane. These local coordinates, \( z \), are obtained from the actual coordinates, \( r \), by applying a unitary rotation matrix \( U \):
\[ r_s - \Gamma_s = U_s z, \]
\[ r_{s+ds} - \Gamma_{s+ds} = U_{s+ds} z. \]
We choose the first unit vector in the local coordinate system to be normal to the hyperplane. The hyperplane constraint, \((r_s - \Gamma_s) \cdot n_s = 0\), can then be written as \( z_1 = 0 \). The first column of \( U_s \) is \( n_s \).

The free energy difference corresponding to an increment \( ds \) in the reaction coordinate is \( dA = -k_B T \ln \left( \frac{Q_{s+ds}}{Q_s} \right) \) where
\[ Q_s = \int e^{-\beta V_s(z)} \delta(z_1) dz, \]
\[ Q_{s+ds} = \int e^{-\beta V_{s+ds}(z)} \delta(z_1) dz. \]
where $Q^\dagger$ is the partition function, taken over the dividing surface, over all system coordinates other than the reaction coordinate.

If the dividing surface, $Z^\dagger$, is specified to be a hyperplane (see Fig. 1) with unit normal vector $\mathbf{n}$ intersecting the path at $\Gamma^\dagger$ and letting $\mathbf{r}$ be the system coordinate in the hyperplane, then the partition function is

$$Q^\dagger = \int e^{-\beta V(\mathbf{r})} \delta \left[ \mathbf{n} \cdot (\mathbf{r} - \Gamma^\dagger) \right] \, d\mathbf{r},$$

(1)

where $V$ is the interaction potential, $\beta = 1/k_B T$, $k_B$ is the Boltzmann constant and $T$ is the temperature of the system. The Dirac $\delta$-function imposes the hyperplane constraint. We will deal only with hyperplanar dividing surfaces in this paper.

2.4. The reaction rate

Once a system has reached the transition region, its rate of escape is $1/t = v_\perp/\delta$, where $t$ is the time it spends there; $v_\perp = \mathbf{v} \cdot \mathbf{n}$ is its velocity perpendicular to the hyperplane. To find the forward flux, only those points in the transition region that are forward-bound should be counted. These comprise half the population there. The escape rate constant is $Q^*/Q^R$ times the average of $1/t$:

$$k = \frac{\langle |v_\perp| \rangle}{2} \frac{Q^\dagger}{Q^R}.$$  

(2)

The factors of $\delta$ in $1/t$ and $Q^\dagger$ have cancelled. Only positive velocities count because back reactions are ignored. The average forward velocity is
\[
\langle |\mu_\perp| \rangle = \frac{k_B T}{\sqrt{2\pi \mu k_B T}}.
\]

(3)

The TST estimate for the rate constant is

\[
k_{\text{TST}} = \frac{k_B T}{\sqrt{2\pi \mu k_B T}} Q^\dagger Q^R.
\]

(4)

Here \(\mu\) is an effective mass for the reaction coordinate.

3. Quantum transition state theory

Several different extensions of classical TST to quantum systems have been proposed [12,19–27]. We will focus here on methods where the classical statistical averaging is replaced by quantum statistical averaging.

3.1. Quantum statistical mechanics

Feynman and Hibbs [6] describe a reformulation of quantum mechanics in terms of Feynman path integrals (FPI). This method involves integrating over all possible paths a system could take from one place to another. If done in real time, it gives quantum dynamics. In imaginary time, it gives quantum statistics. In complex time, it gives a combination of these.

The quantum mechanical partition function, \(Q\), can be written as

\[
Q = \int e^{-V_{\text{eff}}(x(\tau))/k_B T} D\tau(x),
\]

(5)

where \(D\tau(x)\) includes \(P\) integrals over coordinates \(x(\tau) \approx \{x_1, x_2, \ldots, x_P\}\) comprising cyclic paths. The paths are represented to resolution \(P\) in this discrete approximation. Each path contributes to \(Q\) according to its effective potential energy, \(V_{\text{eff}}\) [6,28]:

\[
V_{\text{eff}} = \sum_{i=1}^{P} \left[ \frac{k_{\text{spr}}(x_i - x_{i-1})^2}{2} + \frac{V(x_i)}{P} \right],
\]

(6)

with the spring constant given by \(k_{\text{spr}} = mP/\hbar^2\beta^2\) where \(m\) is the particle mass and \(\beta = 1/k_B T\). Eq. (5) becomes exact as \(P \to \infty\).

The classical system has effectively been replaced by \(P\) images of itself. Each image is subject to forces \(1/P\) as strong as the classical system and interacts with its neighbors through the harmonic springs. In the classical limit as the mass or temperature become larger, \(k_{\text{spr}} \to \infty\), and the stiff springs prevent any delocalization. The \(P\) images combine to give back the original classical system.

With \(P = 1\) the classical approximation is recovered. For \(P > 1\), the springs allow the chain to delocalize, which gives quantum statistical effects. If the chain is at a barrier, it can drape down on either side to sample a lower effective potential; this represents tunneling. If the chain is confined in a small area (as is a particle in a box), it will have fewer available arrangements, which gives it a lower entropy. This confinement entropy corresponds to zero-point energy.

3.2. Centroid density based QTST

A rate theory for transitions in quantum systems based on FPI was introduced by Gillan [12]. He calculated the thermal equilibrium probability density of the quantum particle at various locations by introducing a constraint on the system, fixing the centroid of the FPI chain.
Fig. 2. The system confined to a hyperplane experiences a gradual change in the potential energy as the hyperplane is moved along the reaction path. (a) A schematic contour plot of a potential energy surface with the reaction path shown as a thick solid line. Two different locations of the hyperplane are indicated along the progression from reactants to products. They intersect the reaction path at $I_x$ and $I_x+dz$ and their orientation is given by the normal vectors $n_x$ and $n_x+dz$ as shown in the inset. (b) Potential energy curves corresponding to the two hyperplanes. This illustrates the ramping of the potential experienced by the system confined to stay within the hyperplane, as the hyperplane is moved from one location to another.
From the point of view of a system confined within the hyperplane, the potential energy changes as the reaction coordinate is incremented

\[ V_s(z) \equiv V(r_s), \]
\[ V_{s+dz}(z) \equiv V(r_{s+dz}). \] (14)

This ramping of the potential energy of the system is illustrated in Fig. 2. Since the planes are nearby,

\[ V_{s+dz}(z) = V_s(z) + \delta V(z), \] (15)

where \( \delta V(z) \) is small for all values of \( z \) the system is likely to visit.

The partition function ratio is

\[ \frac{Q_{s+dz}}{Q_s} = \frac{\int e^{-\beta V_s(z)} e^{-\beta \delta V(z)} \delta(z_1) dz}{\int e^{-\beta V_s(z)} \delta(z_1) dz}, \] (16)

which can be written as

\[ \frac{Q_{s+dz}}{Q_s} = (e^{-\beta \delta V(z)})_s = e^{-\beta \delta V(z)} + O(\delta V^2), \] (17)

since \( \delta V \) is small. The average is calculated in plane \( Z_s \). Thus, if the partition functions are written in terms of the constant internal coordinate \( z \), moving the hyperplane from one position to another is, in effect, the same as ramping the potential energy seen by a system confined to the hyperplane by an amount \( \delta V(z) \). The free energy change becomes simply the thermal average of the local internal potential ramp \( \delta V(z) \):

\[ dA = \langle \delta V(z) \rangle_s + O(\delta V^2). \] (18)

The external coordinates of the system in the two hyperplane locations are related by

\[ r_{s+dz} - \Gamma_{s+dz} = U_{s+dz} \Gamma'_{s+dz}, \] (19)

Writing \( U_{s+dz} = U_s + \delta U_s, \ U_{s+dz} \Gamma'_{s+dz} = U_s \Gamma'_{s} + \delta U_s \Gamma'_{s} = I + \delta U_s \Gamma'_{s} \) and substituting into the equation above gives, after rearranging,

\[ \begin{align*}
    r_{s+dz} - r_s &= (\Gamma_{s+dz} - \Gamma_s) + \delta U_s \Gamma'_{s} (r_s - \Gamma_s) \\
    &= n_s dz + \delta U_s \Gamma'_{s} (r_s - \Gamma_s),
\end{align*} \] (20)

using the fact that we chose the normal to be tangent to the path, Eq. (10). The first column of \( U_s \) is \( n_s \).

The other columns can be assigned arbitrarily; the free energy of the plane is independent of them. These column vectors \( u_i \) comprise an orthonormal basis for the hyperplane. The geometrical difference between the two locations of the hyperplane is entirely specified by \( \Gamma'_s, \Gamma'_{s+dz}, n_s, \) and \( n_{s+dz} \). We will now show that the free energy change can be expressed entirely in terms of this geometry, without explicit calculation of the internal basis vectors.

If \( D \) is the dimensionality of the primary system (3\( N_p \) in a three-dimensional system), then

\[ \delta U_s = \begin{bmatrix}
    dn_s & du_2 & \cdots & du_D \end{bmatrix}. \] (21)

Since \( u_i, u_j = \delta_{ij} \) for an orthonormal basis, \( \frac{d}{dz}(u_i, u_j) = 0 \). This property makes the matrix \( \delta U_s \Gamma'_{s} \) antisymmetric.

\[ \delta U_s \Gamma'_{s} = \begin{bmatrix}
    dn_s & du_2 & \cdots & du_D \end{bmatrix} \times \begin{bmatrix}
    n_s \\
    u_2 \\
    \vdots \\
    u_D
\end{bmatrix}. \]
Writing, for convenience, \( n_z \) as \( u_1 \), and making use of the antisymmetry, this can be written as

\[
\delta U_z U_z^T = \begin{bmatrix}
-\sum \frac{\partial u_3 u_2}{\partial n_z} & -\sum \frac{\partial u_3 u_1}{\partial n_z} & \cdots & -\sum \frac{\partial u_3 u_D}{\partial n_z} \\
-\sum \frac{\partial u_2 u_1}{\partial n_z} & 0 & \cdots & -\sum \frac{\partial u_2 u_D}{\partial n_z} \\
\vdots & \vdots & \ddots & \vdots \\
-\sum \frac{\partial u_D u_1}{\partial n_z} & -\sum \frac{\partial u_D u_2}{\partial n_z} & \cdots & 0
\end{bmatrix},
\]

where \( u_{ij} \) is the \( j \)th component of the \( i \)th basis vector.

Operating with this matrix on the vector \( R \equiv r_s - \Gamma_s \) yields, after rearrangement,

\[
\delta U_z U_z^T(R) = -\sum_i u_i (du_i \cdot R).
\] (22)

The internal potential energy ramp is

\[
\delta V(z) = V(r_{s+ds}) - V(r_s) = -F(r_s) \cdot (r_{s+ds} - r_s) \\
= -F(r_s) \cdot n_z ds - F(r_s) \cdot (\delta U_z U_z^T(R)) \\
= -F(r_s) \cdot n_z (ds - dn_s \cdot R) + \sum_{i=2}^{D} (F \cdot u_i) (du_i \cdot R).
\] (23)

The thermal average of each term in the sum over the in-plane basis vectors is zero, \( \langle (F \cdot u_i) (du_i \cdot R) \rangle = 0 \). Since the unit basis vector \( u_i \) is orthogonal to its change \( du_i \), the average of the product is the product of the averages, \( \langle (F \cdot u_i) \rangle = 0 \) for any in-plane \( u_i \), whether or not any orthogonal coordinates are specified. \( \langle du_i \cdot R \cdot (F \cdot u_i) \rangle \) is therefore individually zero for each specified \( du_i \cdot R \), and the overall average vanishes.

The angle between the planes’ normal vectors, \( n_z \) and \( n_z + ds \), is \( d\theta = ||dn_z|| \). The first-order curvature of the reaction path \( \Gamma \) at \( s \) is \( \kappa = d\theta/ds \). We write for the normal component of the force, \( F_n \equiv F(r_s) \cdot n_z \), and for the turning-direction component of the distance from the reference point, \( R_t \equiv (r_s - \Gamma_s) \cdot dn_s/d\theta \). Then we can write the free energy difference between the planes as

\[
dA(s) = -\langle F_n (1 - \kappa R_t) \rangle_s ds.
\] (24)

Here \( \langle F_n R_t \rangle_s \) is the average torque opposing the rotation of the plane around the reference point \( \Gamma_s \) in the direction \( dn_s/d\theta \). The amount of work required to rotate the plane by \( d\theta \) in this direction is

\[
dA_{rot}(s) = \langle F_n R_t \rangle_s d\theta = \kappa \langle F_n R_t \rangle_s ds.
\] (25)

The free energy difference between the reference hyperplane, \( Z^R \), and a hyperplane \( Z_s \) corresponding to reaction coordinate \( s \) is

\[
\Delta A(s) = -\int_R^s \langle F_n (1 - \kappa R_t) \rangle_{s'} ds'.
\] (26)

If all coordinates are specified, the instantaneous force is the mean force. The line integral of the instantaneous force is the potential energy. The reversible work involved in shifting the system from one completely specified configuration to another is just the potential energy difference.

4.2. Implementation of the method

First a reaction path leading from the reactant to the product region is defined. A sequence of hyperplanes intersecting the path is then defined. The hyperplanes must be spaced closely enough for the first order
expression, Eq. (18), to be accurate enough. The average force and torque acting on the system confined to the hyperplane are then statistically sampled and the results integrated according to Eq. (26).

A convenient choice for the path is the minimum energy path (MEP), but any path that does not lead to large numerical cancellations in the force evaluation can be used. The hyperplane normals can conveniently be chosen to be tangent to the path (as we have done here), but this is not necessary. To collect the average force acting on the system in each of the hyperplanes, a Monte Carlo or a molecular dynamics simulation can be carried out subject to the constraint that the system remains in the hyperplane. More specifically, considering a primary system consisting of \( N_p \) atoms in three dimensions, a \( 3N_p \)-dimensional unit vector, the hyperplane normal \( n_s \), is used to constrain the dynamics. At each time step the component of the force vector normal to the hyperplane, \( F \cdot n_s \), is collected for the evaluation of the thermal average, \( \langle F_n \rangle \). But then, this component is projected out of the force to give a new, revised force \( F^{\text{rev}} = F - F \cdot n_s n_s \) which is used in the simulation giving the statistical sampling.

We have used the velocity Verlet algorithm to carry out the molecular dynamics sampling of canonical phase space [31]. The constrained dynamics conserve energy as long as the constraint vector is constant. The optimal dividing surface \( Z^+ \) for the TST rate estimate is the hyperplane \( Z_0 \) corresponding to the maximum free energy, where force \( \langle F_n \rangle \) and the torque \( \langle F_n R_t \rangle \) acting on the hyperplane both vanish. It might be necessary to adjust the orientation of the hyperplane at and near the transition state in order to zero the torque. Alternatively, the path can be redefined to construct a “zero torque path” as we have done for an Eckart barrier test problem [10]. As we will show below, the torque acting on the MEP-constructed hyperplane in the hydrogen dissociative adsorption simulation turns out to be very small, leading to negligible rotational contribution to the free energy barrier.

Each plane has a certain free energy, \( \Delta A(s) \), relative to the reference plane in the reactant state. This free energy gives a TST estimate for the rate, treating that plane as the dividing surface:

\[
k_{s}^{\text{TST}} = \frac{k_B T}{\sqrt{2\pi \mu k_B T}} \frac{Q_s}{Q_R} = \frac{k_B T}{\sqrt{2\pi \mu k_B T}} \frac{Q_R}{Q_R^{Z_0}} e^{-\beta \Delta A(s)}.
\]  

(27)

The plane for which this estimated rate is lowest is the planar dividing surface at which there are the fewest recrossings. So VTST is accomplished automatically by the reversible work calculation. At some plane crossing the reaction path, the free energy will be a maximum; this gives the VTST rate estimate. The automatic inclusion of VTST is an advantage of the reversible work method.

The free energy barrier found this way is path-independent as long as the planes near the barrier are good dividing surfaces. The optimal planar dividing surface is the one corresponding to maximum free energy, and therefore has zero average force and torque acting on it. If there is a net torque on the best plane of the sequence, it can be rotated against the torque, picking up some additional free energy, until the torque is zero.

The idea of using a one-parameter sequence of generalized dividing surfaces and minimizing the calculated rate constant with respect to the parameter has been implemented by Garrett and Truhlar in a semiclassical version of variational transition state theory [17]. Although their methods employ different calculations of the rate than the current work, the idea of optimizing the rate along a path is equivalent to the determination of the hyperplane giving the maximum free energy in the present method.

5. Reversible work formulation of quantum TST

The formulas derived for classical TST will now be generalized to quantum systems by using quantum statistical mechanics instead of classical statistical mechanics to estimate the free energy barrier. The central question is how to incorporate the constraints on the system; i.e., how to confine the system to a hyperplane. Following Gillan [12] we represent each quantum particle in the system with a Feynman path integral and
apply the constraints to the centroids of the path integrals instead of the atom coordinates as in the classical case see Fig. 3).

The hyperplane constraint then becomes

$$Z_s = (\bar{r}_0 - \Gamma_s) \cdot n_s = 0,$$

(28)

where $\bar{r}_0$ is a vector containing the centroid coordinates of quantum atom FPIs. Using a discrete representation of the paths, the centroid for atom $k$ is

$$\bar{r}_0^k = \frac{1}{P} \sum_{i=1}^{P} r^k(i),$$

(29)

where the sum extends over all the FPI images of atom $k$. The reaction’s progress is written in terms of the FPI centroids of the quantum mechanical atoms in the primary system. Therefore, the same reaction path can be used as in the classical calculation.

The quantum mechanical partition function for a hyperplane at $s$ is:

$$Q_s = \int e^{\beta \epsilon_0(s)} \delta [n_s \cdot (\bar{r}_0 - \Gamma_s)] \, Dr(\tau),$$

(30)

with $V_{\text{eff}}$ given by Eq. (6). Just as in the classical case, the change in the hyperplane free energy $\Delta A(s)$ can be evaluated. The quantum mechanical generalization of Eq. (28) is

$$\Delta A(s) = - \int_R \left\{ \frac{1}{P} \sum_{i=1}^P F_n(i) \left[ 1 - \kappa R_s(i) \right] \right\} d\tau,$$

(31)
where the hyperplane statistical average is
\[ \langle \cdots \rangle_s = \frac{\int D\tau \ e^{-\beta \mathcal{H}_a} \cdots \delta\left[n_z \cdot (\vec{r}_0 - \Gamma_z)\right]}{\int D\tau \ e^{-\beta \mathcal{H}_a} \delta\left[n_z \cdot (\vec{r}_0 - \Gamma_z)\right]} \]  \hspace{1cm} (32)

In the appendix we prove that the in-plane components of the force on the images do not contribute to \( \Delta A(s) \), just as in the classical case.

The integration along the reaction path gives a free energy maximum and thereby the free energy barrier for the transition in the quantum system. The transition rate is then obtained from the free energy barrier as in the classical case. Again, the reversible work calculation automatically includes variational maximization of the hypersurface free energy. The transition rate obtained by this reversible work method is exactly the same as the variationally optimized rate for a hyperplar dividing surface obtained in the MSG theory \([24,25]\), but the advantage of the present method is that a solvable reference system for the transition state is not required.

There is no rigorous justification for this formulation of QTST. Other formulations of a quantum generalization of TST have been proposed. The relationship between the estimate obtained from the QTST presented here and the exact reactive flux \([32]\) is unclear. The rate constant for a quantum system calculated by this and other centroid methods has not been proven to give an upper bound to the rate in general. It has been found that optimization of the dividing surface leads to a strict upper bound on the rate in the harmonic limit as well as in a symmetric Eckart barrier test problem \([10,24]\). However, \( k^{QTST} \) has in some other cases been found to be smaller (but only slightly smaller) than \( k^{exact} \) \([24]\).

6. Dissociative sticking of hydrogen on surfaces

We now turn to the application of the reversible work TST method to the dissociative sticking problem. The calculation of the sticking coefficient described here include all six \( \text{H}_2 \) degrees of freedom quantum mechanically as well as eight Cu surface atoms and full thermal averaging over several hundred substrate degrees of freedom. However, the calculations are done within TST and therefore apply to sticking of thermalized hydrogen gas, not molecular beam experiments with selected initial states of the molecules. The large number of degrees of freedom can be included at the expense of detailed dynamical information about the system.

Campbell et al. \([9]\) measured the sticking coefficient of thermally equilibrated hydrogen gas on \( \text{Cu}(110) \) experimentally. These measurements give an activation energy of 0.62 eV in the range 500 to 700 K. Molecular beam experiments convolved to yield a thermal distribution give similar results \([33]\). Also, the activation energy for thermal desorption of \( \text{H}_2 \) from \( \text{Cu}(110) \) has been measured by Anger et al. \([34]\). The results of our simulation are compared to these experimental measurements below.

6.1. The “hole model” for sticking

While TST is most often applied to transitions involving large energy barriers, the foundation of TST requires only that the rate of transition is slow enough to allow the remaining reactants to stay at thermal equilibrium; and that once the dividing surface has been crossed, it will not be recrossed on the time scale of the transition. A bottleneck in phase space involving only an entropic barrier can satisfy these conditions – an energy barrier is not necessary.

As an example, the TST assumptions apply well to an ideal gas in a box effusing through a small hole. There is no energy barrier, just an entropy barrier. Most atoms colliding with the wall will fail to escape because the hole is much smaller than the box’s cross-section. If the box volume is \( V \) and the hole has cross sectional area \( A \), then \( Q^f / Q^R = A/V \) and the TST estimate for the effusion rate is
Table 1
Properties of the empirical interaction potential

<table>
<thead>
<tr>
<th>Characteristic</th>
<th>Experimental</th>
<th>Fitted</th>
</tr>
</thead>
<tbody>
<tr>
<td>( H_2 )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Separation (Å)</td>
<td>0.737</td>
<td>0.740</td>
</tr>
<tr>
<td>Binding energy (eV)</td>
<td>-4.747</td>
<td>-4.7472</td>
</tr>
<tr>
<td>Vibration (eV/Å[2])</td>
<td>24.50</td>
<td>25.43</td>
</tr>
<tr>
<td>H–Cu(110)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Binding energy (eV) [7,34]</td>
<td>-2.3</td>
<td>-2.29</td>
</tr>
<tr>
<td>Vibration (eV/Å²) [38]</td>
<td>5.5</td>
<td>5.0</td>
</tr>
<tr>
<td>( \text{Longbridge saddlepoint} )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Saddle point energy (eV)</td>
<td></td>
<td>+0.688</td>
</tr>
<tr>
<td>H–H separation (Å)</td>
<td>1.3385</td>
<td></td>
</tr>
<tr>
<td>H–Cu height (Å)</td>
<td>0.8802</td>
<td></td>
</tr>
</tbody>
</table>

\[
N_{\text{K,TST}} = \frac{A\rho k_B T}{\sqrt{2\pi\mu k_B T}} = \frac{AP}{\sqrt{2\pi\mu k_B T}}.
\]

which is precisely the rate given by kinetic theory.

A successful model of molecular adsorption, the "hole model" [35,36] is analogous to the effusion problem. The assumption there is that a molecule approaching the surface with the right orientation will adsorb. However, most orientations of the molecule are unfavorable and lead to a large potential barrier which reflects the molecule back into the gas phase. The transition rate is then estimated as the ratio of the volume of the hole relative to the total volume available to the incoming molecule. If the hole model is a reasonable model for dissociative sticking, then TST can be expected to give a good estimate of the sticking probability.

6.2. The \( H_2–\text{Cu(110)} \) potential energy surface

A simple form for the potential function was used to speed up the calculation. An EAM-type [37] potential form was chosen and fitted to data for the \( H_2 \) dimer and the chemisorbed hydrogen. It was also fitted to a grid of points taken from a semi-empirical LEPS potential [38], which is expected to have the right shape qualitatively, as it includes overlap and exchange effects. However, the potential barrier was adjusted to have a much higher saddle point than in Ref. [38]. The potential barrier was scaled up to 0.688 eV, close to the estimate of Hand and Harris based on ab initio calculations [39]. (See Table 1.)

The EAM form works well for copper. With a filled d band, Cu exhibits little directional bonding. Most of the electron density seen by a neighbor is due to the 4s electron.

The EAM potential form is:

\[
V = \sum_{ij} \phi(r_{ij}) + \sum_i F(\rho_i),
\]

where \( \phi \) is a pair potential that represents the screened Coulomb repulsion between the ion cores, including the inner electrons, and \( F(\rho) \) is the energy of embedding an ion core into a valence electron gas of density \( \rho \). The electron density \( \rho_i \) at atom \( i \) is the sum of the contributions of all its neighbors, \( j \):

\[
\rho_i = \sum_j \rho^A(r_{ij}),
\]

where \( \rho^A(r_{ij}) \) is fitted to be the Hartree–Fock atomic electron density.
Table 2
Parameters of the interaction potential (units of eV and Å)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Cu</th>
<th>H</th>
<th>Cu-H</th>
</tr>
</thead>
<tbody>
<tr>
<td>D_A</td>
<td>2862</td>
<td>79.50</td>
<td>86.15</td>
</tr>
<tr>
<td>$\alpha_A$</td>
<td>3.512</td>
<td>2.480</td>
<td>4.211</td>
</tr>
<tr>
<td>D_B</td>
<td>-109.1</td>
<td>-107.6</td>
<td>1.536 E+04</td>
</tr>
<tr>
<td>$\alpha_B$</td>
<td>1.756</td>
<td>2.999</td>
<td>6.076</td>
</tr>
<tr>
<td>S</td>
<td>0.273</td>
<td>2.144</td>
<td></td>
</tr>
<tr>
<td>$\beta_A$</td>
<td>3.691</td>
<td>3.777</td>
<td></td>
</tr>
<tr>
<td>$\beta_B$</td>
<td>7.381</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>$\eta$</td>
<td>6</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>$\gamma$</td>
<td>512</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>$f_1$</td>
<td>-112.9</td>
<td>-81.75</td>
<td></td>
</tr>
<tr>
<td>$f_2$</td>
<td>8510</td>
<td>838.7</td>
<td></td>
</tr>
<tr>
<td>$f_3$</td>
<td>-2.617 E+05</td>
<td>-3953</td>
<td></td>
</tr>
<tr>
<td>$f_4$</td>
<td>4.780 E+06</td>
<td>8768</td>
<td></td>
</tr>
<tr>
<td>$f_5$</td>
<td>-5.234 E+07</td>
<td>-6599</td>
<td></td>
</tr>
<tr>
<td>$f_6$</td>
<td>3.391 E+08</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$f_7$</td>
<td>-1.201 E+09</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$f_8$</td>
<td>1.796 E+09</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

We have chosen the following functional forms

$$
\phi(r_{ij}) = D_A e^{-\alpha_A r_{ij}} + D_B e^{-\alpha_B r_{ij}},
$$

$$
F(p_i) = \sum_{m=1}^M f_m p_i^m,
$$

$$
\rho^\lambda(r_{ij}) = S r_{ij}^{\eta} \left( e^{-\beta_A r_{ij}} + \gamma e^{-\beta_B r_{ij}} \right).
$$

(36)

$\phi(r_{ij})$ is a pair potential that represents the screened Coulomb repulsion between the ion cores. It is parametrized as a double exponential. Each type of pair interaction (Cu–Cu, H–H, and H–Cu) has its own parameter set \{D_A, \alpha_A, D_B, \alpha_B\}. The parameters for the pair potential, the embedding energy and the electron density are given in Table 2.

The pair potential and the electron density are shifted in such a way that they become zero at and beyond a cutoff distance, $R_{\text{cut}}$, chosen to be 6.1 Å.

6.3. Finding minimum energy path using nudged elastic band method

The MEP is defined by the boundary conditions, and by the requirement that the force at any point be parallel to it. That is, for any direction $p_z$ perpendicular to the path, $p_z \cdot \frac{d}{dz} \Gamma_z = 0$, the potential energy is at a minimum: $p_z \cdot \nabla V(\Gamma_z) = 0$.

The boundary conditions are that the MEP must start at the lowest-energy reactant state and finish in the lowest-energy product state. For the H$_2$/Cu problem, the former has the dimer distant from the surface at its equilibrium separation; the latter has the hydrogens on neighboring sites in the same groove on the (110) surface.

The "nudged elastic band" method [40] was used to find the path. This method finds the MEP variationally. An elastic band, made of beads connected by harmonic springs, is strung between the reactant and product states. Using a set of images or replicas of the system to define a discrete transition path, the problem is turned into a minimization problem by defining an object function.
\[ F(r_1, r_2, \ldots, r_{P-1}) = \sum_{i=1}^{P-1} V(r_i) + \sum_{i=1}^{P} \frac{kP}{2} (r_i - r_{i-1})^2, \]

where the first sum is over the “true” potential of all the intermediate images of the system, and the second sum is an “elastic glue” or “spring energy” that keeps adjacent images together. The end point images \( r_0 \) and \( r_P \) are fixed. Although this chain is in some ways analogous to the off-diagonal density matrix \( \text{FPI} \), the MEP is found with no reference to quantum mechanics. Here, the spring constant is arbitrary except that it should scale as \( kP \) to ensure convergence to the MEP as more images are introduced in the chain, \( P \to \infty \) [40].

In order to accelerate the convergence of the chain to the MEP we introduce “nudging”. The component of the net spring force on a bead parallel to the local path tend to keep the bead equidistant from its neighbors; whereas the perpendicular spring force tends to make it collinear with its neighbors. When the MEP is curved, the perpendicular spring force will tend to pull the chain off the MEP, thereby inducing corner cutting. We therefore zero the perpendicular component of the spring force. Each bead also feels a force due to the gradient of the “real” potential energy. The component of this gradient force perpendicular to the path tries to pull the beads down toward the MEP; whereas its parallel component tries to pull the beads down toward either the reactant or product state, away from the saddle point. This effect would result in reduced resolution at the saddle point. We therefore zero the parallel component of this gradient force. Moving each bead in the direction of its adjusted force until the adjusted force becomes zero will put the beads on the MEP (to within the chain’s resolution), equally spaced in the \( 3N_p \)-dimensional space. The technique is not a global search: if there is more than one MEP, only one will be found.

Fig. 4 shows a MEP for the \( \text{H}_2/\text{Cu} \) problem. The initial state is asymmetric with the final state. Even so, the path becomes symmetric in the vicinity of the surface, lining up with the groove on the (110) surface. The nudged elastic band method has therefore shown that the MEP is symmetric. In a six-dimensional system, this is a non-trivial result.

Because of the symmetry found for the MEP, a contour plot of the potential surface characterizes the path quite well. Constraining the \( \text{H}–\text{H} \) axis to be parallel to the surface and aligned with a surface groove, and fixing the \( \text{H}_2 \) center of mass above a long-bridge site, the two remaining variables are \( Z \), the \( \text{H}_2 \) dimer’s height above the surface, and \( R \), the \( \text{H}–\text{H} \) separation. Fig. 5 shows a contour plot of the \( \text{H}_2/\text{Cu} \) potential energy surface, \( V(Z, R) \), with the \( \text{H}_2 \) geometry restricted in this way. The surface configuration is fixed at the minimum energy for a bare surface. The energies are in eV relative to the bare surface and two separated hydrogen atoms.

6.4. Statistical sampling of the hyperplanes

The hyperplane constraints derived from the MEP become quite simple due to the symmetry. Taking the \( x \) axis to be along the rows of atoms on the (110) surface, the \( y \) axis across the rows, and the \( z \) axis normal to the surface, the hyperplane constraint derived from the MEP becomes \( \tilde{z}_1 + \tilde{z}_2 = \text{constant} \) in the reactant state and \( \tilde{x}_1 - \tilde{x}_2 = \text{constant} \) in the product state. Here \( \tilde{x}_1 \) is the \( x \) coordinate of hydrogen 1st centroid, etc. In the intermediate hyperplanes the constraint is

\[ a(\tilde{x}_1 - \tilde{x}_2) + b(\tilde{z}_1 + \tilde{z}_2) = 0, \]

where \( a \) and \( b \) are constants. This means that within the transition state hyperplane, for example, the centroids are allowed to move closer together only if they simultaneously descend toward the surface. They are allowed to move apart only if they ascend higher above the surface. This constraint prevents the atoms from either chemisorbing on adjacent lattice sites, or desorbing. The plane constraint does not affect symmetric motion along the groove (a change in \( \tilde{x}_1 + \tilde{x}_2 \)), asymmetric vertical motion (\( \tilde{z}_1 - \tilde{z}_2 \)) or the \( y \) coordinates perpendicular to the groove. The plane also does not prevent individual images from desorbing or adsorbing as much as the springs between them will allow.
Fig. 4. The minimum energy path between the molecular hydrogen outside the surface and the dissociated hydrogen chemisorbed on adjacent sites on the Cu(110) surface. The Nudged Elastic Band method was used to find the optimal path. The initial state, shown in the upper left panel, was arbitrarily chosen to have the molecule oriented with its axis normal to the surface plane and located directly above a surface atom. The final state, shown in the upper right panel, has the H atoms sitting in fourfold sites separated by a long bridge. Along the minimum energy path, shown in the lower panel, the molecule shifts over to the the long bridge site and turns to make the axis parallel to the surface. The path from then on is symmetric and involves motion perpendicular to the surface and perpendicular to the long bridge. The molecule breaks up very close to the surface.

Fig. 6 shows scatterplots of the H–H orientations in the classical statistical sampling at $T = 100$ K. Plotted are the angles theta and phi of the H–H orientation, relative to the surface. Theta is the polar angle, between 0 and $\pi$. Phi is the azimuthal angle, between $-\pi$ and $\pi$. Fig. 6a is for a hyperplane in the reactant region. There is no restriction on the orientation of the molecule from the hyperplane constraint. There are fewer points at low and high values of theta because most of the surface area of a sphere is found near the equator, at theta $\approx \pi/2$. The scatterplot, when drawn as a rectangle, is therefore not uniform. In Fig. 6b is taken at the the transition state hyperplane where the rotation is highly constricted by the EAM interaction potential. This orientational confinement of the molecule in the transition state contributes to a significant entropy barrier for the transition.

In the quantum statistical sampling, the two H atoms and eight Cu atoms nearest to the H atoms are included as FPI chains. We have used $P = 50$ images in each FPI chain in the present calculations. Fig. 7 shows three snapshots of the FPI chains from the quantum statistical sampling of the transition state hyperplane at $T = 100$ K. The system consists of two hydrogen atoms in the same groove of the Cu(110) surface, across the long bridge. The great flexibility available to the images in the H atom FPIs is evident. For illustration purposes only 20 beads where included in the FPI chains in this figure.

The hyperplane constraint is a very loose constraint, allowing the system to sample a wide range of config-
Fig. 5. Potential energy contours for the dissociation of H₂ on Cu(110) over a long bridge site. Because of the high symmetry of the MEP shown in Fig. 4, a two-dimensional cut through the six-dimensional surface effectively describes the energetics. The molecule is coming down parallel to the surface and is symmetrically arranged over a long bridge site; z is the height above the surface and R the intramolecular distance.

Fig. 6. Scatter plot of the orientation of the H₂ molecule in the statistical sampling of the classical system at T = 100 K. Theta is the polar angle, between 0 and π. Phi is the azimuthal angle, between −π and π. (a) Points taken from the sampling of a hyperplane near the reactant region. The hyperplane constraint does not restrict the rotation of the molecule. (b) Points taken from the sampling of the transition state hyperplane, illustrating the rotational confinement of the molecule due to the H₂–Cu interaction potential.

6.5. The free energy barriers

The accumulated free energy difference with respect to the reactant state as the hyperplane is moved along the reaction path in a classical statistical sampling is shown in Fig. 8. The free energy rises faster than the potential energy along the reaction path. The free energy barrier increases with temperature, indicating a drop in entropy.
as the system approaches the transition state. The intercept of an Arrhenius line from several temperatures gives
\[ \Delta S = -3.4k_B. \]

This drop in entropy at the transition state is a result of the confinement of the molecule (see Fig. 6) by the interaction with the surface as well as confinement of the lattice vibrations due to the presence of the molecule. The two effects were studied separately by first holding the lattice rigid and sampling only the degrees of freedom of the hydrogen molecule (Fig. 9a); and then holding the hydrogen molecule fixed on the MEP while sampling statistically over the lattice degrees of freedom (Fig. 9b). In the second case the rotational-vibrational entropy in the 5 in-plane degrees of freedom of the hydrogen molecule has been removed. The free energy becomes much closer to the MEP potential and has little temperature dependence, corresponding to \[ \Delta S = -1.2k_B. \] The effect of the molecular confinement with the lattice rigid is much larger,
corresponding to $\Delta S = -5.3k_B$. The two effects are not additive. The dynamics and relaxation (amounting to ca. 0.15 Å displacement of the surface Cu atoms) reduce the confinement of the H$_2$ molecule in the transition state, thereby lowering the net entropy barrier for the dissociative sticking. In other words, the movable lattice restricts the hydrogen dimer by a smaller amount than does the rigid lattice. The lattice dynamics therefore assist the reaction by lowering the entropic barrier.

The results of the quantum statistical sampling are shown in Fig. 10 for several different temperatures. The low temperature curves are flat-topped near the transition state. This is a tunneling effect; it is a consequence of the chain’s delocalization. The images drape down over the barrier and manage to avoid the barrier top. Fig. 11 compares the free energy curves for quantum H$_2$, quantum D$_2$, and the classical H$_2$, at 100 K. The deuterium curve shows clear tunneling effects, but smaller than hydrogen, as expected. The accumulated free energy in the quantum statistical sampling also drops below the classical free energy even before the tunneling region is reached. This is evidently a zero-point energy effect due to the softening of the H–H vibration.

We have used a total of 45 hyperplanes to evaluate the free energy barrier. In the first hyperplane the center of the molecule is 7 Å above the surface. The spacing between the hyperplanes was not even as can be seen from the data points in Fig. 8. Initially the spacing is large since the force is small far from the Cu surface. The accuracy of this discretization of the hyperplane progression and the numerical integration of the force was tested by recalculating the free energy barrier using only every other hyperplane. At 100 K, the integrated free energy barrier differed by 0.0002 eV in the classical simulation and by 0.016 eV in the quantum simulation. The error due to finite hyperplane spacing is largest in the low-temperature quantum calculation where tunneling is most significant, because the free energy curve is flat-topped and has a rapidly changing derivative at the onset of tunneling.

A larger source of error in the free energy calculation are statistical errors due to the limited simulation time in calculating the average force. This error is greatest in the high-temperature quantum simulations where the timestep needs to be very small. From the standard deviation in the force acting on the hyperplanes, we estimate...
Fig. 9. Free energy curves obtained in classical statistical sampling after freezing out selected degrees of freedom of the system. (a) The lattice is made rigid to illustrate the effect of confinement of the H2 molecule as the transition state is approached. The entropy barrier becomes larger when the lattice is rigid (compare with Fig. 8), illustrating that relaxation in the lattice relieves the confinement of the molecule in the transition state. (b) The dimer is held rigid on the reaction path while the lattice degrees of freedom are sampled. The molecule confines the lattice vibrations significantly only at high temperatures, $T > 300$ K.

the standard deviation in the accumulated value of the free energy barrier to be 0.03 eV in the quantum results at 600 K, which is the case with largest statistical fluctuations.
Fig. 10. Quantum statistical sampling of the hyperplane along the reaction path (quantum mechanical extension of the results in Fig. 8) showing a significantly lower free energy barrier at low temperature as compared with the classical statistical sampling. Already at $T = 300$ K quantum effects have lowered the free energy barrier by ca. 0.1 eV. At 100 K the barrier is flat-topped due to large tunneling effects. The free energy curve drops below the potential energy curve early along the reaction path, well before tunneling is effective, due to lowering of the zero point energy of the molecule.

Fig. 11. The accumulated free energy at $T = 100$ K for a quantum statistical sampling of D$_2$ dissociative adsorption The classical and quantum sampling of H$_2$ dissociative adsorption from Figs. 8 and 10 is shown for comparison. The classical sampling gives the same results for D$_2$ and H$_2$. This shows that significant lowering of the free energy barrier is found for D$_2$, but smaller than for H$_2$. 
6.6. Tunneling

In an effort to separate the tunneling effect from the effect of changes in zero-point energy, the RMS delocalization perpendicular to the hyperplane was evaluated. The RMS delocalization of a free atom in one dimension, as determined by recursive Gaussian integration [6] of the quantum partition function and taking the limit as \( P \to \infty \), is

\[
\sqrt{\langle (x - \bar{x})^2 \rangle} = \hbar / \sqrt{12mk_BT},
\]

(39)
i.e., inversely proportional to the square root of both temperature and mass. For a hydrogen atom at 100 K, this is 0.2 Å.

Fig. 12a shows the average RMS delocalization perpendicular to the hyperplane as a function of the reaction coordinate for \( H_2 \) at 100 K and at 300 K. At 100 K the delocalization suddenly increases, in the space of one hyperplane, to a much higher value in the barrier region. This delocalization is the source of the flat-topped free energy barriers at low temperatures and is a clear signature of tunneling.

The temperature where tunneling becomes important can be estimated from the curvature of the potential barrier. Consider a chain with its centroid atop a one-dimensional parabolic barrier. The images will spread away from the barrier top as far as the spring constant allows. The barrier top is thus not as unfavorable for a quantum atom as it is for a classical atom. The centroid density at the barrier top is correspondingly increased, and any reaction that goes over the barrier will proceed faster than expected. This corresponds to tunneling.

The effective energy of a given configuration \( x(\tau) \), which determines the Boltzmann sampling of configurations with \( V(x) \) a parabolic barrier potential \( V = -kx^2/2 \) is

\[
V_{\text{eff}}[x(\tau)] = \sum_{i=1}^{P} \left[ \frac{k_{\text{spr}}(x_i - x_{i-1})^2}{2} - \frac{1}{P} \frac{k(x_i)^2}{2} \right].
\]

(40)

Both the spring energy and the barrier potential scale as distance squared. Thus, if the distances of all beads from the center are doubled \((x_i \to 2x_i)\), both the spring energy and the barrier energy are quadrupled. If the spring constant \( k_{\text{spr}} \) is small compared to the barrier sharpness \( k \), \( V_{\text{eff}} \) is negative. Then \( V_{\text{eff}} \) decreases without bound as the beads move away from the barrier, and the chain delocalizes to infinity in both directions.

In practice, when the springs are weak, the chain runs away from the barrier top until the barrier starts curving back up. The critical temperature, in terms of the imaginary barrier frequency \( \Omega \equiv k/\mu \), turns out to be \( k_B T_c = \hbar \Omega / (2\pi) \) [12]. This is a reasonable estimate of the temperature at the onset of tunneling. Below \( T_c \), the chain delocalization near the barrier is expected to be significantly larger than in free space.

Fig. 12b shows the difference in RMS delocalization between the reactant and transition state at a range of temperatures, for \( H_2 \) and \( D_2 \). Significant increase in the delocalization sets in at about 400 K for hydrogen and at about 300 K for deuterium, as the temperature dependent spring constants in the FPI become weaker than the curvature of the MEP potential barrier. Using the curvature of the MEP potential barrier to estimated in the onset of increased delocalization the equation for \( T_c \) above, gives \( T_c = 400 \) K for \( H_2 \), and \( 290 \) K for \( D_2 \), in good agreement with the observed behaviour.

The onset temperature of tunneling delocalisation is well predicted from a parabolic barrier reference, but the delocalization turns out to increase smoothly as the temperature is lowered further, while the parabolic barrier model predicts a very sharp cutoff temperature below which the delocalization goes to infinity. The gradual increase in the delocalization is due to the anharmonicity of the MEP potential. As the FPI images start probing regions where the barrier becomes significantly non-parabolic a balance is reached between the downward push from the potential gradient and the upward pull from the springs connecting to images on the other side of the barrier top. Thereby the tunneling delocalization saturates. Fig. 13 shows the distribution of FPI images for hydrogen projected onto the MEP in typical snapshots taken from the statistical sampling at 100 and 300 K.
Fig. 12. (a) The RMS delocalization of H₂ perpendicular to the hyperplane as a function of the reaction coordinate. In a free H atom the delocalization is 0.2 Å at 100 K. As the repulsive interaction between the molecule and the surface sets in the delocalization decreases. Near the transition state, a dramatic increase in the delocalization is observed at 100 K due to tunneling. In this segment of the reaction path, the free energy is nearly constant (see Fig. 11). At 300 K, the delocalization is much weaker but still noticeable. (b) The difference in the RMS delocalization perpendicular to the transition state hyperplane and the delocalization of free H₂ molecule and D₂ molecule as a function of inverse temperature. Straight lines fitted to the larger values are shown only to guide the eye. Significant increase in the delocalization sets in at about 400 K for hydrogen and at about 300 K for deuterium, as the temperature dependent spring constants in the FPI become weaker than the curvature of the MEP potential barrier.
Even at 300 K where the tunneling effect is small, the FPI images already probe regions where anharmonic effects are clearly significant.

In H$_2$ at 300 K, the change in RMS delocalization between initial and transition states (see Fig. 12b) is small. However, the actual delocalization is about 0.12 Å. The delocalization goes to zero at high temperature, but very reluctantly, as an inverse square root. The quantum system therefore is not expected to become truly classical except at extremely high temperatures.

However, the quantum system at moderate temperatures such as 300 K behaves quasi-classically: the delocalization remains roughly constant, and the distribution of images remains roughly spherical. The system's statistics correspond roughly to those of a classical system at the same temperature, but whose potential energy surface has been shifted to account for the zero-point energy effects seen at the non-zero delocalization. In other words, the quantum effects at moderate temperatures, though non-zero, may simply show up as an implicit shift in the potential energy, rather than as the fundamental differences that are observed at low temperatures.

6.7. Torque contribution to the reversible work

The rotational contribution to the reversible work turns out to be small for this system. Fig. 14 shows the accumulated free energy difference due to rotation of the hyperplanes as a function of the reaction coordinate. While the curvature of the path is quite large, the torque with respect to the MEP is small and the net effect on the free energy is small. This is unlike the Eckart barrier plus harmonic oscillator model system, where the rotational contribution was found to be just as large as the translational contribution when using the MEP as reaction path [10]. There, tunneling caused the average density to move off the MEP and thereby create torque on the hyperplane in a region of large path curvature. By redefining the path to coincide roughly with the average density, the torque on the hyperplane and thereby the rotational contribution to the free energy was minimized. The net free energy barrier, however, was the same.
Fig. 14. Rotational contribution to the free energy as a function of reaction coordinate at $T = 100$ K. The contribution is negligible as compared with the translational contribution in this system when the MEP is chosen to be the reaction path, because the torque acting on the hyperplanes turns out to be very small. A small but statistically significant contribution is obtained where the path curvature is largest, near the transition state. Quantum delocalization effects result in a shift of the average density of the system with respect to the MEP which presumably changes the direction of the torque and thereby the sign of the rotational contribution to the free energy.

While the rotational contribution is small here, it is statistically significant, and of opposite sign in the classical and quantum case (Fig. 14). Quantum delocalization effects result in a shift of the average density of the system with respect to the MEP, which presumably changes the direction of the torque and thereby the sign of the rotational contribution to the free energy.

6.8. Activation energy for adsorption and desorption

Fig. 15 shows an Arrhenius plot for the calculated free energy barriers to dissociative adsorption. The classical statistical sampling gives a straight line corresponding to a constant activation energy of 0.73 eV. Both H$_2$ and D$_2$ are observed to be classical at 600 K, but below 400 K the quantum results deviate from the classical results. The quantum statistical sampling gives significantly lower free energy barriers below 400 K, and a correspondingly lower activation energy of 0.38 eV for H$_2$ and 0.45 eV for D$_2$. A near Arrhenius behaviour is observed in the quantum regime as well as in the classical regime; the calculated points fall close to a straight line fit. The lowering of the activation energy is mainly due to tunneling, as illustrated by the delocalization perpendicular to the hyperplane shown in Fig. 12b. The tunneling isotope effect is $(0.73 - 0.38)/(0.73 - 0.45) = 1.25$.

The experimental data of Campbell and coworkers is also shown in Fig. 15. The measured activation energy agrees well with the calculated results, but the measured sticking probability is larger by a factor of 40, indicating the entropy barrier is too large in the simulation and the model potential should be adjusted to have a wider reaction channel at the transition state. If we assume the in-plane vibrations are harmonic, this can be accomplished, for example, by reducing all five frequencies by a factor of $1/40^{1/5} \approx 1/2$. This takes into account only the five non-reactive hydrogen vibrations (such as symmetric translation in the groove of the (110) surface, symmetric and antisymmetric vibrations perpendicular to the groove, and antisymmetric vertical motion) and neglects modifications in the copper vibrations. Since the shape of our model potential surface is quite arbitrarily derived from the LEPS potential form with no direct experimental input determining the width
Fig. 15. An Arrhenius plot for H₂ and D₂ dissociative adsorption. The calculated points are for 100, 150, 200, 300, 400, and 600 K. The classical statistical sampling gives a straight line corresponding to a constant activation energy of 0.73 eV. The quantum statistical sampling gives significantly lower free energy barriers below 400 K and a correspondingly lower activation energy of 0.38 eV for H₂ (slope of large dashed line) and 0.45 eV for D₂ (slope of small dashed line). The lowering of the activation energy is mainly due to tunneling. The experimental data of Campbell and coworkers [7] is shown with triangles. The measured activation energy agrees well with the calculated results, but the measured sticking probability is larger by a factor of 40, indicating the entropy barrier is too large in the simulation and the model potential should be adjusted to have a wider reaction channel at the transition state. A line is drawn through the calculated points only to guide the eye.

of the reaction channel at the transition state, such a modification is not unreasonable.

Fig. 16 shows an Arrhenius plot for the reverse reaction, recombinative desorption. The classical statistical sampling gives Arrhenius type behaviour with the calculated points falling near a straight line corresponding to a constant activation energy of 0.55 eV. The quantum statistical sampling gives significantly lower free energy barriers below 400 K, and a correspondingly lower effective activation energy. The calculated points do not fall on a straight line, as is typical for decay of metastable states, and the effective activation energy is therefore somewhat temperature dependent. At 300 K the calculated activation energy is 0.49 eV for H₂. An experimental activation energy has been reported by Anger [34] as 0.43 eV in this temperature range and in the zero coverage limit. The calculated and measured activation energies are therefore in quite good agreement. The activation energy at 100 K is calculated to be significantly lower, down to 0.36 eV. Again, tunneling through the barrier has a strong effect at low temperature.

6.9. Classical dynamical corrections

The transmission coefficient, \( \kappa \), can be calculated by molecular dynamics [8,16]. An ensemble of points is found at the dividing surface whose momenta are Boltzmann-distributed and initially forward-directed. The ensemble is propagated forward and backward in time until all its members leave the vicinity of the transition state. The fraction of these trajectories which actually started in R and finish in P is counted. We assume that once the system leaves the vicinity of the transition state, it will remain either a reactant or a product for a much longer time than it spent near the transition state. If, however, it spends a long time in the intermediate
region, dynamical corrections become problematic.

Classical dynamical correction calculations were carried out for H\textsubscript{2} and D\textsubscript{2} at 600 K, where classical statistical sampling gave the same TST rate estimate as quantum statistical sampling. An ensemble of 144 points was taken at the transition state hyperplane; each of these was assigned a Boltzmann velocity and each trajectory was followed forward and backward in time until it left the transition state region. TST assumes that each crossing point will finish as products when propagated forward and as reactants when propagated backward. If, for a given crossing point, either of these assumptions is untrue, it does not count toward the rate. The transmission coefficient was found to be $\kappa = 0.54 \pm 0.08$ for H\textsubscript{2} and $\kappa = 0.56 \pm 0.08$ for D\textsubscript{2}. No kinetic isotope effect was observed for this system.

A transmission coefficient of 0.5 has the same effect on the rate as does a free energy increase of $-k_B T \ln \kappa = 0.03$ eV at 600 K. This is of the same magnitude as the error associated with calculation of the free energy. More careful estimations of $\kappa$ are therefore not called for unless the free energy difference is also calculated significantly more accurately.

None of the trajectories lingered in the transition region for more than a picosecond. The quantum dynamics are expected to be similar to the classical dynamics at this high temperature, and the quantum transmission coefficient will, therefore, likely be within an order of magnitude of the classical transmission coefficient, corresponding to a few hundredths of an eV. The free energy difference would then provide a good estimate of the sticking coefficient, even without dynamical corrections. Furthermore, since the classical trajectories spent little time near the transition state, it may be feasible to do a quantum dynamical calculation for the short time required to estimate corrections to the QTST estimate. However, we expect those corrections to be small, and conclude from the classical dynamical corrections that TST is an excellent approximation for treating the H\textsubscript{2} dissociative adsorption as well as associative desorption at a Cu(110) surface. Other dissociative adsorption
processes are likely to be also well approximated by TST.

7. Conclusions

We have presented a calculation of the dissociative sticking and thermal desorption of hydrogen molecules using a statistical approach, quantum transition state theory, where the two hydrogen atoms were included fully quantum mechanically and a thermal average was carried out over both the molecular and surface degrees of freedom. For the model potential surface used here, the system crosses over from classical to quantum behaviour at about $T = 400$ K for H$_2$ and $T = 300$ K for D$_2$. In the quantum regime, the activation energy is significantly reduced, the free energy barriers are flat-topped, and the delocalization is significantly greater at the barrier than in the reactant state, indicating that tunneling becomes the dominant transition mechanism.

A practical method for evaluating the required free energy barriers in classical and quantum systems has also been given. This method is based on a reversible work evaluation and can be applied with relative ease to systems of high dimensionality. Another advantage of this method is the identification of an optimal, hyperplanar dividing surface for the TST rate estimate in the course of the reversible work calculation.

Acknowledgements

This work is supported by the Division of Chemical Sciences, Office of Basic Energy Sciences, US Department of Energy under Grant No. DE-FG06-91ER14224 (G.M. and H.J.) and under Contract No. DE-AC06-76RLO 1830 with Battelle Memorial Institute which operates the Pacific Northwest Laboratory (G.S.). G.M. acknowledges support from the Hertz foundation and ARCS foundation.

Appendix A

In this appendix we show that the contributions to the free energy difference between two hyperplanes due to the in plane forces vanishes in the quantum mechanical case, just as in the classical case. We start with the rotational component of Eq. (18). Using Eq. (19) this can be written as

$$dA_{\text{rot}}(s) = \left\langle \int_0^{\beta \hbar} \frac{d\tau}{\beta \hbar} \nabla V[r(\tau)] \cdot U_s^T U_s (r(\tau) - \Gamma_s) \right\rangle ds. \tag{A.1}$$

With the transformation to local coordinates, $z$, given by Eq. (12), this expression may be rewritten in terms of the rotated coordinates $z$ as

$$dA_{\text{rot}}(s) = \left\langle \int_0^{\beta \hbar} \frac{d\tau}{\beta \hbar} \frac{\partial V[z(\tau)]}{\partial z} \cdot U_s^T U_s z(\tau) \right\rangle ds, \tag{A.2}$$

where the average is written in terms of $z$ as

$$\langle \cdots \rangle_z = \frac{\int Dz(\tau)e^{-\frac{\beta \hbar}{2}\int \delta(z(\tau))_1}}{\int Dz(\tau)e^{-\frac{\beta \hbar}{2}\int \delta(z_0)_1}}. \tag{A.3}$$

Consider the following average where $i \neq 1$ and $j \neq i$.
\[ I_{ij} = \left\langle \int_0^{\beta\hbar} d\tau \frac{\partial V[\zeta(\tau)]}{\partial z_i} z_j(\tau) \right\rangle. \]  
(A.4)

In terms of a path integral, this becomes

\[ I_{ij} = C \int D\zeta(\tau) e^{-S/\hbar} \int_0^{\beta\hbar} d\tau \frac{\partial V[\zeta(\tau)]}{\partial z_i} z_j(\tau) \delta[(\zeta_0)_1], \]  
(A.5)

where \( C \) is a normalization constant.

Using the following relation

\[ \frac{\partial S}{\partial (\zeta_0)_i} = \int_0^{\beta\hbar} d\tau \frac{\partial V(\zeta(\tau))}{\partial z_i}, \]

we may write

\[ I_{ij} = -\frac{C}{\beta} \int D\zeta(\tau) \frac{\partial}{\partial (\zeta_0)_i} \left[ e^{-S/\hbar} z_j(\tau) \delta[(\zeta_0)_1] \right]. \]  
(A.6)

\( I_{ij} \) can be shown to be zero in the following way. First introduce

\[ G = \left[ e^{-S/\hbar} z_j(\tau) \delta[(\zeta_0)_1] \right] \]  
(A.7)

so that \( I_{ij} \) can be written as

\[ I_{ij} = -\frac{C}{\beta} \int D\zeta(\tau) \frac{\partial}{\partial (\zeta_0)_i} G \]  
(A.8)

and

\[ G \to 0 \text{ as } (\zeta_0)_i \to \pm \infty. \]  
(A.9)

By transforming to Fourier variables

\[ \tilde{z}_k = \frac{1}{\hbar\beta} \int_0^{\hbar\beta} d\tau e^{-i\Omega_k \tau} \zeta(\tau), \]  
(A.10)

where

\[ \Omega_k = \frac{2\pi k}{\hbar\beta}, \]  
(A.11)

Eq. (A.6) becomes

\[ I_{ij} = -\frac{C}{\beta} J \left[ \prod_{(k,l) \neq (0,i)} \int d(\tilde{z}_k)_l \right] \int d(\tilde{z}_0)_i \frac{\partial}{\partial (\zeta_0)_i} G, \]  
(A.12)

where \( J \) is a constant Jacobian for the transformation.
\[ \int Dz(\tau) = J \prod_{(k,l)} \int d(\bar{z}_k)_l. \] (A.13)

We next do the \((\bar{z}_0)_i\) integration to give
\[ I_{ij} = -\frac{C}{\beta J} \left[ \prod_{(k,l) \neq (0,0)} \int d(\bar{z}_k)_l \right] (G(+\infty) - G(-\infty)) \, ds, \] (A.14)

which verifies
\[ I_{ij} = 0. \]

Using this result and the fact that \(U_s^T U'_s\) is antisymmetric, gives
\[ dA_{rot}(s) = \left\langle \frac{\beta \hbar}{\beta \hbar} \left[ \frac{\partial V[z(\tau)]}{\partial z_1} \right] \right\rangle \left[ U_s^T U'_s z(\tau) \right]_1 ds, \] (A.15)

which can be rewritten as
\[ dA_{rot}(s) = -\left\langle \frac{\beta \hbar}{\beta \hbar} \left[ \frac{\partial V[r(\tau)]}{\partial r} \cdot U_s \right] \right\rangle \left[ U_s^T (r(\tau) - \Gamma_s) \right]_1 ds, \] (A.16)

and with \([U_s]_{ii} = [n_s]_i\), we recover our final result
\[ dA_{rot}(s) = -\left\langle \frac{\beta \hbar}{\beta \hbar} \left( \frac{\partial V[r(\tau)]}{\partial r} \cdot n_s \right) \right\rangle \left( n'_s \cdot (r(\tau) - \Gamma_s) \right) ds, \] (A.17)

which is equivalent to Eq. (25) derived for the classical case.

References

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[41] The analogous figure in Ref. [9] is different because the potential energy curve shown there is for a frozen substrate and does not correspond to the MEP. Also, there are slight differences in the interaction potential and the coupling to the thermal bath between the present calculations and Ref. [9] leading to small differences in the calculated results.